

# EVALUATION OF FUNCTIONS

Notes prepared for EE 6481

by

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## EVALUATION OF FUNCTIONS

- Sensitivity of the computed value of a function to changes in the values of the arguments

Example: Roots of a polynomial

- Newton-Raphson method for finding roots
- Numerical integration
- Other methods for evaluating functions include:
  - Evaluation of series (see slides on floating-point computation)
  - Solution of ordinary differential equations
  - Solution of partial differential equations

## SENSITIVITY/CONDITION NUMBER (1)

- **Sensitivity** of the value  $f(x, y)$  of a function  $f$  to changes in the input  $y$ :

$$S(f; x, y) := \left| \frac{y [f(x, y) - f(x, y)]}{(y - y) f(x, y)} \right|$$

$$\left| \frac{y}{f(x, y)} \frac{f(x, y)}{y} \right|$$

Also known as the **condition number**

$S$  is the ratio of the relative errors in the output and the input:

$$S = \frac{f/f}{y/y}$$

Example:  $f(x, y) = x - y$

$$S(f; x, y) = \frac{|y|}{|x - y|}$$

## SENSITIVITY/CONDITION NUMBER (2)

- Sensitivity of the value of a repeated root of a polynomial to changes in the constant term:

$$p(z, c) := \sum_{k=1}^n \binom{n}{k} z^k (-1)^{n-k} + c$$

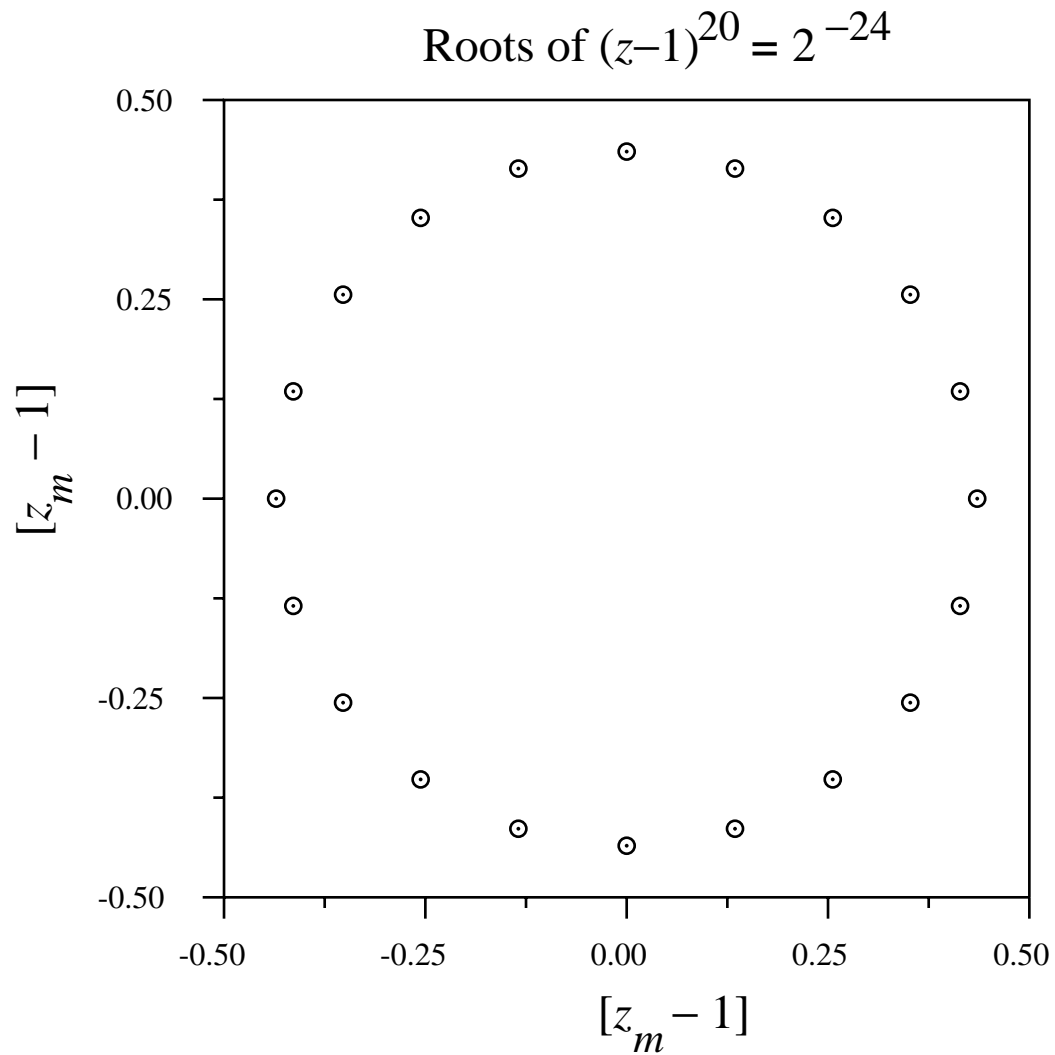
$$p(z, (-1)^n) = (z - 1)^n \quad n \text{ roots, each equal to } 1$$

One **ulp** (unit in the last place) is  $u = 2^{-24}$  in IEEE-754 single precision

Sensitivity of the roots of  $p(z, c)$  to a change of one ulp near  $c = 1$ :

$$S(z_1; c) = \left| \frac{[z_1(c) - z_1(1)]}{(c - 1) z_1(c)} \right| \left| \frac{u^{1/n}}{u} \right| = \frac{1}{u^{(n-1)/n}} \frac{1}{u} = 1$$

**SENSITIVITY/CONDITION NUMBER (3)**



## NEWTON-RAPHSON METHOD (1)

- The Newton-Raphson method is one of the better iterative methods for finding roots of a function  $f$

Let  $a$  be a zero of  $f$ ; if  $x \neq a$ , then

$$f(x) \approx f(a) + (x - a)f'(a)$$

$$a \approx x - \frac{f(x)}{f'(x)}$$

**Newton-Raphson method:** Iterate the difference equation

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$

to convergence



## NEWTON-RAPHSON METHOD (3)

- Rate of convergence for

$$f(x) = B(x - a) + C(x - a)^2$$

Difference equation:

$$x_{k+1} = x_k - \frac{(x_k - a) + \frac{C}{B}(x_k - a)^2}{1 + 2\frac{C}{B}(x_k - a)} = a + \frac{C}{B}(x_k - a)^2$$

if  $x$  is sufficiently close to  $a$  that

$$2\frac{C}{B}|x_k - a| < 1$$

If this inequality holds already when  $k = 0$ , then

$$x_{k+1} - a = \left(\frac{C}{B}\right)^k (x_0 - a)^{2k}$$

The number of significant digits doubles with each iteration!

**NEWTON-RAPHSON METHOD (4)**

- Reciprocal approximation instead of floating-point division (used on Seymour Cray's machines)

To find the number  $a$  such that

$$a = \frac{1}{b}$$

one can find the zeros of

$$f(x) = \frac{1}{x} - b$$

Newton-Raphson difference equation:

$$x_{k+1} = x_k - (-x_k + x_k^2 b) = 2x_k - x_k^2 b$$

**NUMERICAL INTEGRATION (1)**

- Problem: Evaluate the Riemann integral

$$I = \int_a^b f(x) dx$$

Sample  $f$  at  $N + 1$  points  $x_0 = a$ ,  $x_1 = a + h$ ,  $\dots$ ,  $x_N = b$  and approximate  $I$  as a weighted sum of sampled values of  $f$

$$I \approx \sum_{i=0}^N w_i f(x_i) = \sum_{i=1}^N I_i$$

where

$$I_i := \int_{x_{i-1}}^{x_i} f(x) dx$$

is the approximate integral of  $f$  over the **panel**  $(x_{i-1}, x_i)$

Common rules for integration:

Newton-Cotes methods (including rectangle rules)

Gaussian quadrature

**NUMERICAL INTEGRATION (2)**

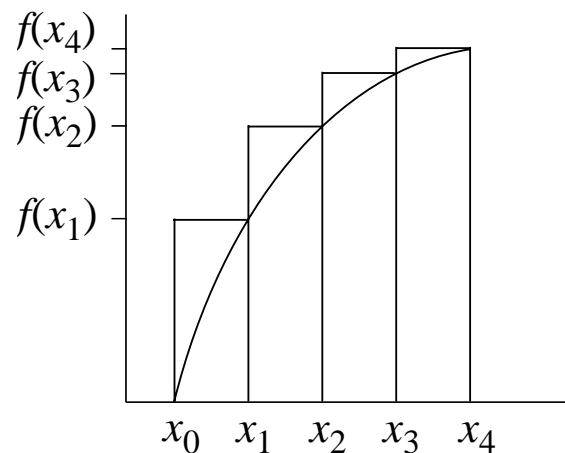
- Rectangle rules: Use a staircase approximation for  $f$

Right-hand rectangle rule:

$$\int_a^b f(x) dx \quad R_h[f] = \sum_{i=1}^N r_i[f]$$

where

$$r_i[f] = h_i f(x_i), \quad h_i = x_i - x_{i-1}$$



**NUMERICAL INTEGRATION (3)**

- Centered rectangle rule:

$$\int_a^b f(x) dx \quad C_h[f] = \sum_{i=1}^N c_i[f]$$

where

$$c_i[f] = h_i f(x_{i-\frac{1}{2}}), \quad h_i = x_i - x_{i-1}, \quad x_{i-\frac{1}{2}} = \frac{x_i + x_{i-1}}{2}$$

- Trapezoidal rule:

$$\int_a^b f(x) dx \quad Th_h[f] = \frac{h}{2} f(x_0) + h \sum_{i=1}^{N-1} f(x_i) + \frac{h}{2} f(x_N)$$

## NUMERICAL INTEGRATION (4)

- Numerical example: Evaluate  $\int_0^1 x^2 dx = \frac{1}{3}$  using 3 different rules and  $h = \frac{1}{4}$

$i$	$f(x_i)$	$f(x_{i-\frac{1}{2}})$
0	0	n/a
1	$\frac{1}{16}$	$\frac{1}{64}$
2	$\frac{1}{4}$	$\frac{9}{64}$
3	$\frac{9}{16}$	$\frac{25}{64}$
4	1	$\frac{49}{64}$
rule	computed integral	error
right-hand rectangle	0.4687	0.1354
midpoint	0.3281	-0.0052
trapezoidal	0.3438	0.0104

Note that the error of the trapezoidal method is  $-2$  times the error of the midpoint method for this example

## LOCAL vs. GLOBAL ERROR IN NUMERICAL INTEGRATION

- Local error in computed value of integral
  - Error after 1 step of integration
  - Equal to computed 1-panel integral – exact 1-panel integral
- Global error in computed value of integral
  - Error after  $N$  steps of integration
  - Equal to algebraic sum of local errors (classical approach)
  - Can also be analyzed by global methods
    - Transfer function (comes from considering numerical integration rule as a digital filter)
    - Numerical dispersion function (  $(k)$ ) vs. physical dispersion function

## LOCAL ERROR ANALYSIS IN NUMERICAL INTEGRATION (1)

- Right-hand rectangle rule (algebraic derivation)

Expand  $f$  about one of the sampling points:

$$f(x) = f(x_i) + \left. \frac{df}{dx} \right|_{x_i} (x - x_i) + \dots$$

Integrate over one panel:

$$\int_{x_{i-1}}^{x_i} f(x) dx = h_i f(x_i) - \frac{1}{2} h_i^2 \left. \frac{df}{dx} \right|_{x_i} + \dots$$

Obtain global error by summing local errors:

$$\int_a^b f(x) dx - R_h[f] = \frac{h^2}{2} \sum_{i=1}^N \left. \frac{df}{dx} \right|_{x_i}$$

$$R_h[f] - h \left( \frac{b-a}{2} \right) \left( \frac{1}{N} \sum_{i=1}^N \left. \frac{df}{dx} \right|_{x_i} \right)$$

## LOCAL ERROR ANALYSIS IN NUMERICAL INTEGRATION (2)

- Right-hand rectangle rule (geometrical derivation)

Local error    area of triangle:

$$\text{local error}_i = \frac{1}{2}h(f(x_i) - f(x_{i-1}))$$

Global error = sum of local errors:

$$\begin{aligned} \text{global error} &= \frac{1}{2}h(f(x_1) - f(x_0) + f(x_2) - f(x_1) + \cdots + f(x_N) - f(x_{N-1})) \\ &= \frac{1}{2}h(f(x_N) - f(x_0)) \end{aligned}$$

Global error    step size times change in  $f$  (in this case)

Note the cool telescoping sum

## LOCAL ERROR ANALYSIS IN NUMERICAL INTEGRATION (3)

- Centered rectangle (midpoint) rule

Expand  $f$  about one of the sampling points:

$$\begin{aligned}
 f(x) = & f(x_{i-\frac{1}{2}}) + \left. \frac{df}{dx} \right|_{x_{i-\frac{1}{2}}} (x - x_{i-\frac{1}{2}}) + \frac{1}{2} \left. \frac{d^2 f}{dx^2} \right|_{x_{i-\frac{1}{2}}} (x - x_{i-\frac{1}{2}})^2 \\
 & + \frac{1}{6} \left. \frac{d^3 f}{dx^3} \right|_{x_{i-\frac{1}{2}}} (x - x_{i-\frac{1}{2}})^3 + \frac{1}{24} \left. \frac{d^4 f}{dx^4} \right|_{x_{i-\frac{1}{2}}} (x - x_{i-\frac{1}{2}})^4 + \dots
 \end{aligned}$$

Integrate a typical term:

$$\int_{x_{i-1}}^{x_i} (x - x_{i-\frac{1}{2}})^p dx = \begin{cases} h_i & \text{if } p = 0; \\ 0 & \text{if } p = 1; \\ \frac{1}{12} h_i^3 & \text{if } p = 2; \\ 0 & \text{if } p = 3; \\ \frac{1}{80} h_i^5 & \text{if } p = 4. \end{cases}$$

## LOCAL ERROR ANALYSIS IN NUMERICAL INTEGRATION (4)

- Centered rectangle (midpoint) rule

Local error:

$$\int_{x_{i-1}}^{x_i} f(x) dx = c_i[f] + p_i[f] + q_i[f] + \dots = t_i[f] - 2p_i[f] - 4q_i[f] + \dots$$

where

$$p_i[f] := \frac{1}{24} h_i^3 \left. \frac{d^2 f}{dx^2} \right|_{x_{i-\frac{1}{2}}}, \quad q_i[f] := \frac{1}{1920} h_i^5 \left. \frac{d^4 f}{dx^4} \right|_{x_{i-\frac{1}{2}}}$$

Obtain global error by summing local errors:

$$\int_a^b f(x) dx = C_h[f] + \frac{h^3}{24} \sum_{i=1}^N \left. \frac{d^2 f}{dx^2} \right|_{x_{i-\frac{1}{2}}}$$

$$C_h[f] + h^2 \left( \frac{b-a}{24} \right) \left( \frac{1}{N} \sum_{i=1}^N \left. \frac{d^2 f}{dx^2} \right|_{x_{i-\frac{1}{2}}} \right)$$

## LOCAL ERROR ANALYSIS IN NUMERICAL INTEGRATION (5)

- Trapezoidal rule

Local error:

$$\int_{x_{i-1}}^{x_i} f(x) dx = c_i[f] + p_i[f] + q_i[f] + \dots = t_i[f] - 2p_i[f] - 4q_i[f] + \dots$$

Note that (3rd order trapezoidal error) =  $-2 \times$  (3rd order midpoint error)

Obtain global error by summing local errors:

$$\int_a^b f(x) dx - T_h[f] = \frac{h^3}{12} \sum_{i=1}^N \left. \frac{d^2 f}{dx^2} \right|_{x_{i-\frac{1}{2}}}$$

$$T_h[f] - h^2 \left( \frac{b-a}{12} \right) \left( \frac{1}{N} \sum_{i=1}^N \left. \frac{d^2 f}{dx^2} \right|_{x_{i-\frac{1}{2}}} \right)$$

## LOCAL ERROR ANALYSIS IN NUMERICAL INTEGRATION (6)

- Simpson's rule

Combine the one-panel formulas for the trapezoidal and midpoint rules so that the 3rd order error vanishes

Let

$$s_i[f] := \frac{2}{3}c_i[f] + \frac{1}{3}t_i[f] = \frac{1}{6}h_i \left[ f(x_{i-1}) + 4f(x_{i-\frac{1}{2}}) + f(x_i) \right]$$

Local error:

$$\int_{x_{i-1}}^{x_i} f(x) dx = s_i[f] + \frac{2}{3}q_i[f] + \dots$$

Obtain global error by summing local errors:

$$\int_a^b f(x) dx - S_h[f] = \frac{b-a}{180} \left( \frac{h}{2} \right)^4 \left( \frac{1}{N} \sum_{i=1}^N \frac{d^4 f}{dx^4} \Big|_{x_{i-\frac{1}{2}}} \right)$$

## LOCAL ERROR ANALYSIS IN NUMERICAL INTEGRATION (7)

- Simpson's rule

Multi-panel rule using a redefined step size  $h = h/2$  and redefined sampling points  $x_{2i} = x_i$ ,  $x_{2i-1} = x_{i-\frac{1}{2}}$ :

$$\int_a^b f(x) dx = \frac{h}{3} (f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + \dots + 4f(x_{2N-3}) + 2f(x_{2N-2}) + 4f(x_{2N-1}) + f(x_{2N})) - \frac{b-a}{180} (h)^4 \left( \frac{1}{N} \sum_{i=1}^N \frac{d^4 f}{dx^4} \Big|_{x_{i-\frac{1}{2}}} \right)$$

Note that the weights oscillate at the Nyquist frequency